



■ Features

- 90~264Vac input, Built-in PFC function
- · Controllable with external controller
- · Fanless design for no-noise and expanding life cycle
- · High surge current 200% up to 5 seconds
- Protections: Short circuit/OCP
- Provided multiple sensors for control: Current sensor- motor torque control DC bus voltage sensor- OVP/UVP Temperature sensor - OTP
- -30~+70°C wide operating temperature
- · Suitable for three phase motor drive (BLDC, Induction motor, SynRM)
- 3 years warranty

Applications

- HVAC
- Fan
- Pump
- Automatic door
- Air condition
- Conveyor
- Medical device
- · Fitness equipment

Description

VFD-350C-230 is a variable frequency drive that can be controlled with external PWM controller. The input range is from 90VAC to 264VAC which is suitable for all kinds of installation. VFD-350C-230 able to deliver 200% peak load and with fan-less design, the life time can be extended. VFD is suitable for three-phase motor drive, such as BLDC, Induction motor, SynRM applications.

Model Encoding

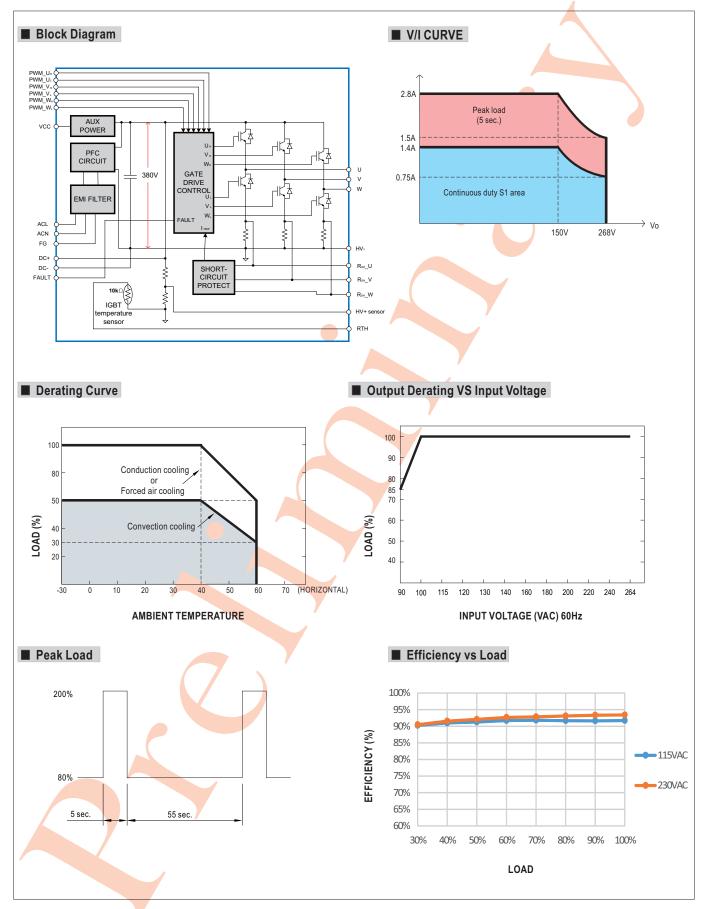
VFD - 350 C - 230 Nominal output voltage Metal case type Wattage

350W General type Variable Frequency Drive with PFC function VFD-350C-230

SPECIFICATION

OUTPUT PEA EFF DC E RAT INPUT POW RAT INVE FAU FAU FAU PROTECTION SHO OUTPUT FREQUENCY SWITH RAT SWITH RAT OUTPUT SWITH RAT SWITH SWITH SWITH SWITH SWITH RAT SWITH SWI	LTAGE RANGE(UVW) Note.1		
OUTPUT RAT PEA EFF DC E RAT INPUT POV RAT INVE FAU FUNCTION (Note.5) DC E THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWITH FEAU SWITH FREQUENCY SWITH FREQUENCY RAT INPUT POV RAT SWITH FAU SWITH FREQUENCY FREQUENCY		Three phase line-to-line 0~240V, suit for 200-240V class motor	
OUTPUT PEA EFF DC E RAT INPUT POV RAT INVE FAU FAU FAU PROTECTION OUTPUT FREQUENCY SWIF REFF PEA EFF DC E THR THE AUX SWIF SWIF REFF PEA EFF DC E THR THE SWIF SWIF SWIF SERVICE SWIF SWI	TPUT CAPACITY	350W	
PEA EFF DC E RAT INPUT POV RAT INVE FAU FAU FAU PROTECTION OUTPUT FREQUENCY SWITTER SWI	TED CURRENT	1.4A	
FUNCTION (Note.5) PROTECTION SHO OUTPUT FREQUENCY RAT INPU RAT INVE FAU FAU THE AUX SWITTER S	AK CURRENT Note.2	2.8A	
INPUT POV RAT INPUT POV RAT INRU INVE FAU FUNCTION (Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWIT	FICIENCY Note.3	93%	
INPUT POV RAT INRI INVE FAU FUNCTION (Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWIT	BUS VOLTAGE	380±5VDC	
FUNCTION (Note.5) POVE THRE AUX PROTECTION SHO OUTPUT FREQUENCY SWITTER SWITTER DOVE THRE SWITTER SWITTER SWITTER POVE THRE SWITTER POVE	TED INPUT VOLTAGE	90 ~ 264Vac	
FUNCTION (Note.5) FAU THE AUX PROTECTION SHO OUTPUT FREQUENCY SWITTER RAT INVE FAU FAU OUTPUT SWITTER SWITTER THE SWITTER SWITTER SWITTER THE SWITTER SWITTER THE SWITTER SWITTER THE SWITTER SWITTER THE SWITTER SWITTER SWITTER THE SWITTER SWITT	UT FREQUENCY RANGE (Hz)	47 ~ 63Hz	
FUNCTION (Note.5) PROTECTION OUTPUT FREQUENCY INVENTAGE FAU FAU AUX SWITTER THE AUX SWITTER SWITTER FREQUENCY	WER FACTOR (Typ.)	PF>0.99/115VAC, PF>0.93/230VAC at full load	
FUNCTION (Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWIT	TED INPUT CURRENT	3.5A /115VAC 2A/230VAC	
FUNCTION (Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWIT	USH CURRENT	Cold start 50A	
FUNCTION (Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWITTER	ERTER PWM INPUT	PWM control signal input for driving inverter IGBTs. (PIN8~13 of CN93) TTL input: IGBT ON: High(>2.6V); IGBT OFF: Low(<0.8V); iin =2mA	
(Note.5) THR THE AUX PROTECTION SHO OUTPUT FREQUENCY SWITE	JLT SIGNAL	Inverter fault signal(Short circuit/OCP, PIN7 of CN93). TTL input: Normal: High(>4.5V); Abnormal: Low(<0.5V)	
PROTECTION SHO OUTPUT FREQUENCY SWIT	BUS VOLTAGE SENSOR	DC BUS voltage sensor output(HV+ sensor, PIN1 of CN93): 2.5V@DC BUS 380V	
PROTECTION SHO OUTPUT FREQUENCY SWIT	REE PHASE CURRENT SENSOR	Built-in 250mΩ low-side shunt resisor (each phase), (PIN4~6 of CN93)	
PROTECTION SHO OUTPUT FREQUENCY SWIT	ERMAL SENSOR	Built-in 10KΩ NTC for sensing IGBTs operating temperature. (TSM2A103F34D1R (Thinking Electronic), PIN2 of CN93)	
OUTPUT FREQUENCY SWIT	XILIARY POWER VCC	Non-isolated 15V output power for user's application. Max current : 0.3A, Ripple:1V	
FREQUENCY	ORT CIRCUIT	Protection type : Shut down o/p voltage, re-power on to recover	
coc	ITCHING FREQUENCY RANGE	2.5KHz ~ 15KHz	
	OLING SYSTEM	Air convection	
WOF	RKING TEMP.	-30 ~ +70°C (Refer to "Dreating Curve")	
ENVIRONMENT WOF	RKING HUMIDITY	20 ~ 90% RH non-condensing	
sто	DRAGE TEMP., HUMIDITY	-40 ~ +85°C, 10 ~ 95% RH non-condensing	
VIBE	RATION	10 ~ 500Hz, 5G 10min./1cycle, period for 60min. each along X, Y, Z axes	
SAF	FETY STANDARDS	Design refer to EN618000-5	
	HSTAND VOLTAGE	I/P-FG:2KVAC	
SAFETY & ISOI	LATION RESISTANCE	I/P-FG:100M Ohms/500VDC/25°C/ 70%RH	
EMC	C EMISSION	Compliance to EN61800-3 Class B, BS EN/EN61000-3-2,-3	
ЕМС	C IMMUNITY	Compliance to EN61800-3	
МТВ	BF	K hrs min. MIL-HDBK-217F (25°C)	
OTHERS DIM	IENSION (L*W*H)	146*55*26mm	
PAC	CKING	0.33Kg	
NOTE 2, E 3. F 4. A 5. F	1. 3-phase 220V motor is recommended. Please consider the rated current when used for 100-120V class motor. 2. Efficiency is tested by 350W with 150VAC output line-to-line voltage. 3. Refer to peak load usage definition. 4. All parameters NOT specially mentioned are measured at 230VAC input, rated load and 25°C of ambient temperature. 5. Please refer to page 4 for more details. ※ Product Liability Disclaimer: For detailed information, please refer to https://www.meanwell.com/serviceDisclaimer.aspx File Name:VFD-350C-230-SPEC 2022-08-08		



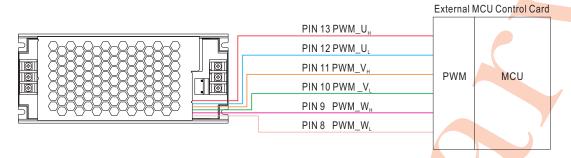




■ Function Manual

1. 3-phase PWM Control

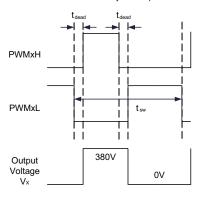
VFD-350C-230 provides six-switch circuit by using 3 half-bridge IGBTs. IGBTs of each phase is controlled by PWM_U,/U, PWM_V,/V, and PWM_W,/W, (PIN 8~13). The input requirement for PWM is compatible with both TTL and CMOS 3.3V signals. Please refer to the diagram below.



t_{dead} (Min.)

300ns

WARNING: It is necessary to keep minimum dead-time 300ns between the upper and lower switch of each phase.

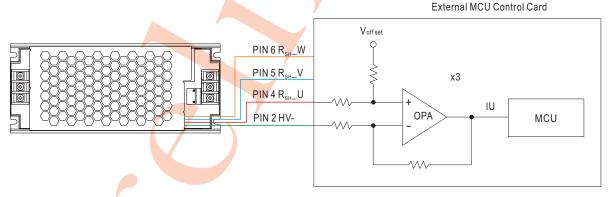


 t_{dead} : Switching Dead time x = U, V, W

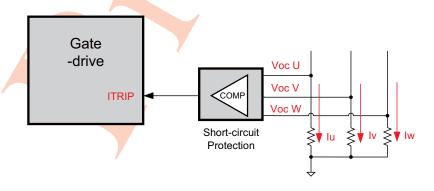
tsw : Switching period

2. DC bus current Detection & Overcurrent Protection

Low-side shunt resistor $250m\Omega$ is installed on DC bus of VFD-350C-230 for current measurement and short-circuit detection. It's suggested to shorten the length of external detection circuit and detect the signal with a OPAs. Please refer to diagram below.

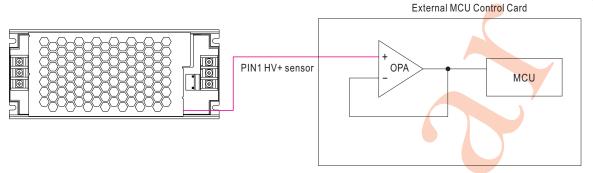


If output current exceed 200% of rated value, the protection circuit will be triggered and shut down the gate driver for protection.



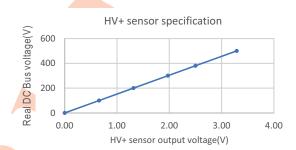
3. DC BUS Voltage Detection

VFD-350C-230 is built-in with DC bus voltage sensor(HV+ sensor, PIN 1). Refer to the recommended circuit. The sensor can provides a 2.5V output when DC bus voltage is at 380V. It's suggested to detect the signal by OPAs. When the voltage of the DC bus exceed 420V, the PWM input signal must shut down for protection.



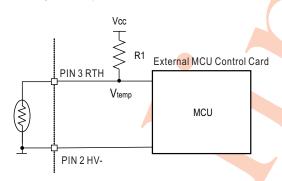
Equation for DC bus voltage calculation:

$$V_{DCBUS} = \frac{380 \times HV + sensor}{2.5}$$



4. IGBT Temperature Detection

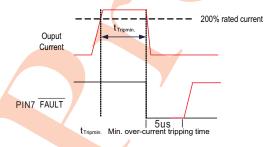
VFD-350C-230 is built-in a NTC resistor for detecting IGBTs temperature. Users can detect IGBTs temperature for protection. (NTC type: TSM2A103F34D1R, Thinking Electronic) The recommended detection circuit is below. It's suggested to shutdown the PWMs input, if the temperature is above 90°C.



It's suggested to shutdown the PWMs input, if the temperature is above 90°€.

5. Driver Fault signal

The FAULT signal would be active (active-low) to notify external controller or circuit, if VFD-350C-230 encounter the overcurrent state and keep the state for minimum overcurrent tripping time





■ Mechanical Specification Unit:mm Case No. 146 140 7.8 TB100 CN100 TB1 4- φ 3.3 L=6

AC Input Terminal Pin NO. Assignment (TB1)

Pin No.	Assignment
1	AC/L
2	AC/N
3	<u></u>

Output Terminal Pin NO. Assignment (TB100)

Pin No.	Assignment
1	U
2	V
3	W

380V DC Bus Connector(CN100): JST B3P-VH or equivalent

Pin No.	Assignment
1	DC+
2	No Pin
3	DC-

Mating housing: JST VHR or equivalent Terminal: JST SVH-21T-P1.1 or equivalent

 CN100 is used for installing regenerative brake device, avoiding VFD-350C-230 damage.

Control Pin NO. Assignment (CN93): HRS DF11-14DP-2DS or equivalent

Pin No.	Assignment	Pin No.	Assignment
1	HV+ sensor	8	PWM_W _L
2	HV-	9	PWM_W _H
3	RTH	10	PWM_V _∟
4	R _{sH} _U	11	PWM_V _H
5	R _{sh} _V	12	PWM_U _∟
6	R _{sH} _W	13	PWM_U _H
7	FAULT	14	VCC

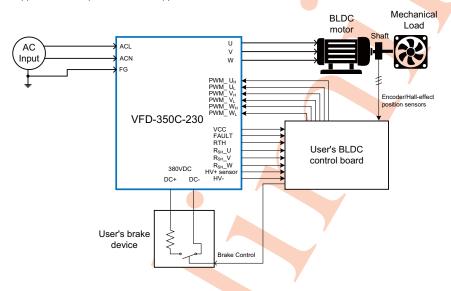
Mating housing: HRS DF11-14DS or equivalent Terminal HRS DF11-**SC or equivalent

※Control Pin No. Assignment(CN93):

Pin No.	Function	Description
1	HV+ sensor	DC BUS voltage sensor output 2.5V, reference to pin 2(HV-)
2	HV-	DC BUS voltage sensor output ground
3	RTH	Temperature sensor
4	R _{sh} _U	U phase current sensor output
5	R _{sH} _V	V phase current sensor output
6	R _{sH} _W	W phase current sensor output
7	FAULT	Over current detection. Normal > 4.5V, Abnormal < 0.5V
8	PWM_W _H	W phase high side logic input, on > 2.6V; off < 0.8V
9	PWM_W _L	W phase low side logic input, on > 2.6V; off < 0.8V
10	PWM_V _H	V phase high side logic input, on > 2.6V; off < 0.8V
11	PWM_V _L	V phase low side logic input, on > 2.6V; off < 0.8V
12	PWM_U _H	U phase high side logic input, on > 2.6V; off < 0.8V
13	PWM_U _L	U phase low side logic input, on > 2.6V; off < 0.8V
14	VCC	Auxiliary voltage output 14.5~15.5V reference to pin(HV-). The maximum load current is 0.3A

■ APPLICATION

Application example: BLDC drive application

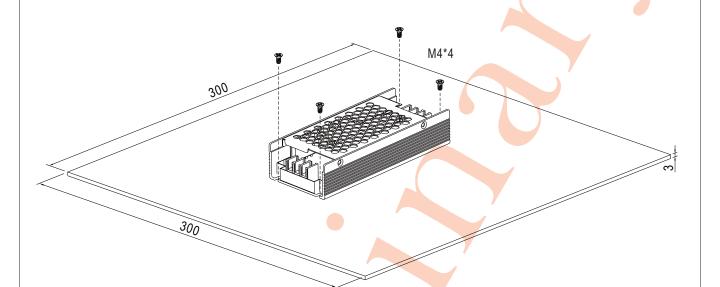


- 1. The figure shows the BLDC drive system which set up with VFD-350C-230.
- 2.Developers can control the PWM signal of 6-switch by using SPWM or SVPWM, etc. for 3-phase voltage modulation, and build the control method base on the current shunt sensors on 3-phase low-side switch(RSHU/V/W) and the DC BUS voltage sensor(HV+ sensor) which provided by VFD-350C-230.
- 3.Developers select the appropriate BLDC position sensors such as encoder or Hall-effect sensors to fit their applications.
- 4.It's suggested to install the brake circuit/device at the DC+/DC-pin(DC BUS) for avoiding the DC BUS OVP when BLDC is decelerating.
- 5.It's suggested to shut down the PWM input or connect to brake resistor device for safety when DC Bus voltage is higher than 420V.
- 6.If VFD-350C-230 were applied non-appropriate control, such as accelerating too quickly or bad current control, it might trig the VFD-350C-230's fault-state to shut down the output voltage(low-level on FAULT pin).

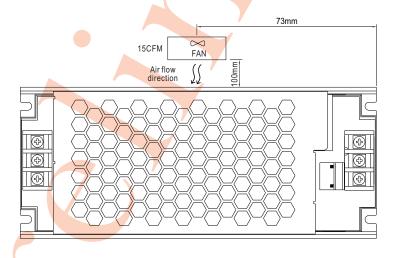


1. Operate with additional aluminum plate

In order to meet the "Derating Curve" and the "Static Characteristics", VFD series must be installed onto an aluminum plate (or the cabinet of the same size) on the bottom. The size of the suggested aluminum plate is shown as below. And for optimizing thermal performance, the aluminum plate must have an even and smooth surface (or coated with thermal grease), and VFD series must be firmly mounted at the center of the aluminum plate.



2.With 15CFM forced air



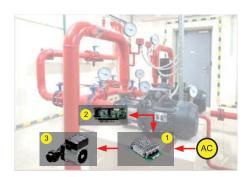


■ ACCESSORY LIST

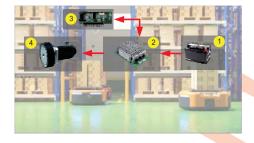
If have any control solution requirement of specific application. Please consult MEANWELL for more details.

MW's order No.	Item	Quantity
VFD-CB Control board (optional)	8 E-0-000 2021/01/2008 2021/01/2008 2021/01/2008	1

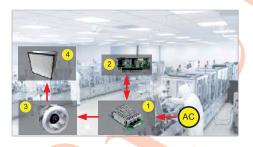
■ TYPICAL APPLICATION



- 1 Variable Frequency Module (VFD series)
- 2 Control board of Variable Frequency Drive (Designed by User or Soluton Provided by MeanWell
- 3 Three-phase Pump Motor



- 1 Battery
- 2 Variable Frequency Module (VFD series)
- 3 Control board of Variable Frequency Drive (Designed by User or Soluton Provided by MeanWell
- 4 Three-phase Wheel Motor for AGV Application



- 1 Variable Frequency Module (VFD series)
- 2 Control board of Variable Frequency Drive (Designed by User or Soluton Provided by MeanWell
- 3 Three-phase Fan Motor
- 4 HEPA for Filtering Air

■ Installation Manual

Please refer to : http://www.meanwell.com/manual.html